

A Constraint-Solving Approach to Faust Program Type Checking

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October 13, 2014

Origin of constraints

- Environment T: mapping of Faust identifiers to their types
- Identifiers' types plugged into the typing rules

Constraints implementation

- Type templates with type variables in the environment
 - + : ((int $[a_1,b_1]$, int $[a_2,b_2]$), (int $[a_1+a_2,b_1+b_2]$))
- Templates implemented by replacing type variables by actual values or unification variables (buffer values)
 - 1 , 1 : + \implies + : ((int [-1,1], int [-1,1]), (int [-2,2]))
- Unification variables = variables for constraints
- Different possible instances, based on subtyping:

1 , 10 : + \implies + : ((int [-1,1], int [-10,10]), (int [-11,11]))

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Predicates syntax

```
p \in \mathsf{P} ::= \text{ true } | e b e

e \in \mathsf{E} ::= i | o_1 e | e o_2 e

b \in \mathsf{B} ::= = | < | \le | > | \ge

o_1 \in \mathsf{O}_1 ::= \sin | \cos | \dots

o_2 \in \mathsf{O}_2 ::= + | - | \dots

i \in \mathsf{I}
```

Constraints syntax

$$c \in \mathsf{C}$$
 ::= (p list , i list) | $c \cup c$

where,

for
$$c = (ps,is)$$
 and $c' = (ps',is') \in \mathbb{C}$, $c \cup c' = (ps @ ps' , is @ is')$

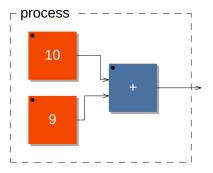
Constrained types

- o constrained_type ::= (expression_type , c)
- Result of the constraint generation part of the type checking algorithm
- Solver input = c
- Solver output = Mapping m from unification variables to values
- Application of *m* to expression_type
 - \implies Type (Global result of the algorithm)

Solver

- Solving handled by existing solvers, using SMT-LIB as a common representation framework for constraints
- Currently using Z3
- Possibility to design a lighter solver, only using theories involved in the algorithm?
- Output = mapping of unification variables to values

```
process = 10,9:+;
```



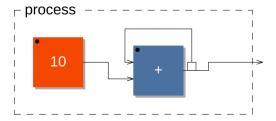
Constrained type = (

Type: ((),((uv13[uv8+uv11,uv9+uv12])^uv14)),

```
Constraint:
((uv1<=10,uv2>=10,uv4<=9,uv5>=9,uv3==uv14,Int==uv7,uv1>=uv8,uv2<=uv9,
uv6==uv14,Int==uv10,uv4>=uv11,uv5<=uv12),
(uv1,uv2,uv3,uv4,uv5,uv6,uv7,uv8,uv9,uv10,uv11,uv12,uv13,uv14)))
```

Type = ((),((Int[19,19])^1))

process = $10:+\sim_{-}$;



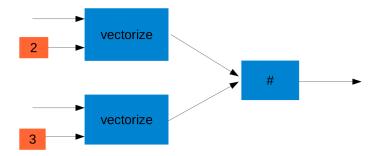
```
Constrained type = (
```

```
Type: ((),((uv10[faust_min-0,faust_max+0])^uv11)),
```

```
Constraint:
((uv1<=10,uv2>=10,uv11==uv15,uv10==uv12,uv5+uv8>=uv13,uv6+uv9<=uv14,uv11==uv15,
uv4==uv12,uv5>=uv13,uv6<=uv14,uv3==uv11,Int==uv7,uv1>=uv8,uv2<=uv9),
(uv1,uv2,uv3,uv4,uv5,uv6,uv7,uv8,uv9,uv10,uv11,uv12,uv13,uv14,uv15)))
```

```
Type = ((),((Int[faust_min-0,faust_max+0])^1))
```

```
process = (_,2:vectorize),(_,3:vectorize):# ;
```



```
process = (_,2:vectorize),(_,3:vectorize):# ;
```

```
Constrained type = (
```

```
Type:
(((uv1[uv2,uv3])^uv4,(uv16[uv17,uv18])^uv19),
((vector_uv34+uv35(uv31[uv32,uv33]))^uv36)),
```

Constraint:

```
((uv5<=2,uv6>=2,uv4==uv14,uv1==uv8,uv2>=uv9,uv3<=uv10,uv7==uv15,Int==uv11,
uv5>=uv12,uv6<=uv12,uv20<=3,uv21>=3,uv19==uv29,uv16==uv23,uv17>=uv24,
uv18<=uv25,uv22==uv30,Int==uv26,uv20>=uv27,uv21<=uv27,uv14/uv12==uv36,
uv12==uv34,uv8==uv31,uv9>=uv32,uv10<=uv33,uv29/uv27==uv36,
uv27==uv35,uv23==uv31,uv24>=uv32,uv25<=uv33),</pre>
```

(uv1,uv2,uv3,uv4,uv5,uv6,uv7,uv8,uv9,uv10,uv11,uv12,uv13,uv14,uv15,uv16,uv17,uv18,uv19,uv20,uv21,uv22,uv23,uv24,uv25,uv26,uv27,uv28,uv29,uv30,uv31,uv32,uv33,uv34,uv35,uv36)))

```
Type = (((Int[0,0])^2,(Int[0,0])^3),((vector_5(Int[0,0]))^1))
```

Conclusion

- Faustine + Faust Type checker = interpreter + type checker for the multirate version of Faust
- Link between the classic typing approach, based on substitutions, and the constraint programming approach
- Future work:
 - Performance statistics on type checking benchmarks
 - ► Constraint solving ⇒ Constraint programming
 - Study of different combinations between the typing and constraint programming approaches
 - Possible case of study: Optimization of the loop case in the Faust syntax
 - Integration into the C++ compiler of Faust



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