BDSC-Based Automatic Task Parallelization: Experiments

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Context and Motivation

- Anyone can build a fast CPU. The trick is to build a fast system. Attributed to Seymour Cray
- Parallelism handling:
 - Parallel software developed by converting sequential programs by hand
 - Automatic task parallelism extraction: Scheduling problem
 - Resource constraints: memory requirements, processor features...
 - Scientific, signal and image processing benchmarks

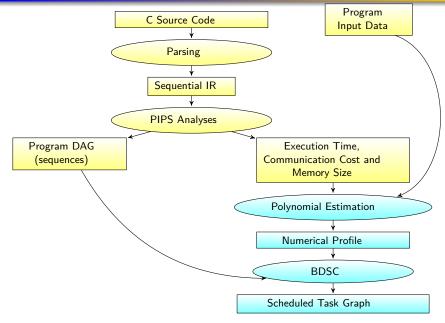
Automatic Resource-Constrained Static Task Parallelization

- **BDSC**: a memory-constrained, number of processor-bounded extension of DSC
- Experimentation on shared and distributed memory systems

- BDSC: A Memory-Constrained, Number of Processor-Bounded Extension of DSC
- 2 Experimental Evaluations with PIPS
- 3 Conclusion and Future Work

Parallelization Process

blue indicates contributions; an ellipse, a process; and a rectangle, results



Contents

BDSC: A Memory-Constrained, Number of Processor-Bounded Extension of DSC

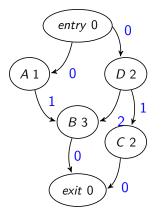
- List-Scheduling Heuristics
- Dominant Sequence Clustering (DSC)
- BDSC: A Resource-Constrained Extension of DSC

2 Experimental Evaluations with PIPS



List-Scheduling Heuristics

- Priorities are computed for all unscheduled vertices using:
 - Top level (tlevel(au)): length of the longest path from entry to au
 - Bottom level (blevel(τ)): length of the longest path from τ to exit



task	tlevel	blevel
D	0	7
С	3	2
A	0	5
В	4	3

- $\bullet~$ Vertex τ with the highest priority is selected for scheduling
- au is added to the cluster (logical process) with the earliest start-time

- DSC (Dominant Sequence Clustering) [Yang and Gerasoulis 1994]
- Task list-scheduling heuristic for an unbounded number of clusters
- priority $(\tau) = tlevel(\tau) + blevel(\tau)$
- zeroing(τ_p , τ) puts τ in the cluster of a predecessor $\tau_p \Rightarrow$ reduces tlevel(τ) by setting to zero the cost of the edge (τ_p , τ)

	\								
(A1)(D2)	$\succ 1$	step	task	tlevel	blevel	prio	scheduled tlevel		
\checkmark 1 \checkmark	\backslash						κ_0	κ_1	κ_2
	¥	1	D	0	7	7	0*		
	\frown	2	С	3	2	5	2	3*	
(B 3) ≮ 2	(C2)	3	Α	0	5	5			0*
		4	В	4	3	7	2*		4

• Complexity: $\mathcal{O}(n^2 \log(n))$

A List-Scheduling Heuristic: Dominant Sequence Clustering (DSC)

• DSC algorithm weaknesses for our purpose:

- Unbounded number of clusters
- $\bullet\,$ Number of clusters is not predefined $\rightarrow\,$ blind clustering
- $\bullet~$ Memory size is not predefined $\rightarrow~$ blind clustering
- Creates long idle slots in already existing clusters

Proposal

BDSC: A Memory-Constrained, Number of Processor-Bounded Extension of DSC

Bounded DSC: Resource Constraint Warranty

1 Memory Constraint Warranty (MCW):

- Do not exceed a memory threshold M
- Overapproximation of the amount of memory used in tasks
- data_size(cluster_data (κ) \cup task_data (au)) \leq M
- Ø Bounded number of clusters P:
 - Number of cluster allocations do not exceed Threshold P
 - Maintain the constraint MCW
 - $\operatorname{argmin}_{k \in clusters} \operatorname{cluster_time}(\kappa)$
- Sefficient cluster allocation by exploiting idle slots
- **4** Complexity: $\mathcal{O}(n^3)$

Related Work: Static Task Parallelization Tools

			Resource	Dependence		Execution	Communica-	Memory
	blevel	tlevel	constraints	control	data	time estimation	tion time estimation	model
BDSC Parallelization	\checkmark	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark	Shared, distributed
Sarkar's work [Sarkar, 1989]	\checkmark				\checkmark	\checkmark	\checkmark	Shared, distributed
OSCAR [Kasahara et al., 1992]		\checkmark		\checkmark	\checkmark	\checkmark		Shared
Pedigree [Newburn and Shen, 1996]	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark		Shared
SPIR [Choi et al., 2009]		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	Shared

BDSC: A Memory-Constrained, Number of Processor-Bounded Extension of DSC

2 Experimental Evaluations with PIPS

- Experimental Setting
- BDSC vs. DSC
- Comparative Study with Faust Parallelizing Compiler



Benchmarks

- Thales ABF (Adaptive Beam Forming), with 1,065 lines
- SPEC benchmark equake, with 1,432 lines
- Harris corner detector, with 105 lines
- NAS Parallel Benchmark IS (Integer Sort), with 1,076 lines

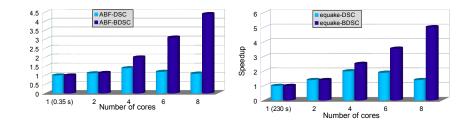
Ø Machines

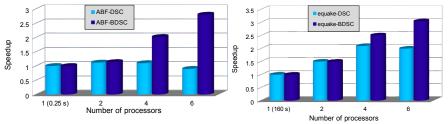
- Shared Memory: host Linux (Ubuntu)
 - 2-socket AMD quadcore Opteron, 2.4 GHz
 - M = 16GB of RAM
 - gcc 4.6.3 -O3
 - OpenMP 3.0
 - $\mathsf{Cluster} \sim \mathsf{Thread}$

• Distributed Memory: host Linux (RedHat) 6 dual-core processors Intel® Xeon®, 2.5 GHz

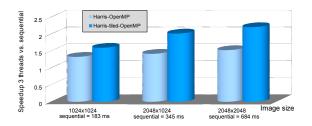
- M = 32GB of RAM per processor
- gcc 4.4.6 -O3
- Open MPI 1.6.2
- $\mathsf{Cluster} \sim \mathsf{Process}$

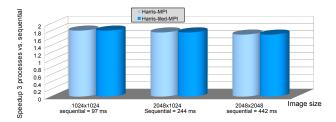
ABF and equake Speedups with OpenMP and MPI





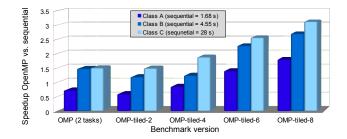
Harris Speedups with OpenMP and MPI: Impact of Tiling (P=3)

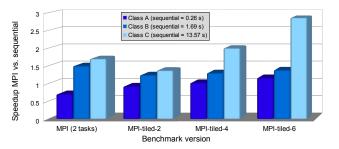




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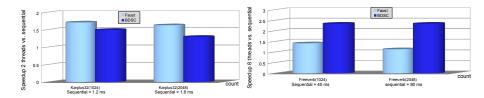
NAS Parallel Benchmark IS Speedups with OpenMP and MPI: Different Class Sizes





Faust Parallel Scheduling vs. BDSC

- Faust (Functional AUdio STream) [Orlarey et al., 2009]
- DSL for real-time audio signal processing and synthesis
- Generation of C or C++ with or without OpenMP directives
- omp task (BDSC) vs. omp section (Faust Parallelizing Compiler)
- Scheduling: BDSC vs. Faust topological ordering
- Speedups for two programs: Karplus32 and Freeverb



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Conclusion

1 BDSC-based hierarchical scheduling algorithm

- Memory constraint, bounded number of clusters, efficient cluster allocation
- BDSC-based task parallelization algorithm
- Communication, data and time cost models

② Experiments:

- BDSC-based automatic parallelization in PIPS
- Code generation in OpenMP and MPI
- Good speedups for coarse-grained parallelism

Future Work

BDSC Scheduling

- Handling of heterogeneous devices
- More precise cost models

2 Parallel Code Generation

- More experimentation needed
- Solving communication generation problems (MPI)
- Hybrid task + data parallelism

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